

Computer-based analysis of rhegmatogenous retinal detachment

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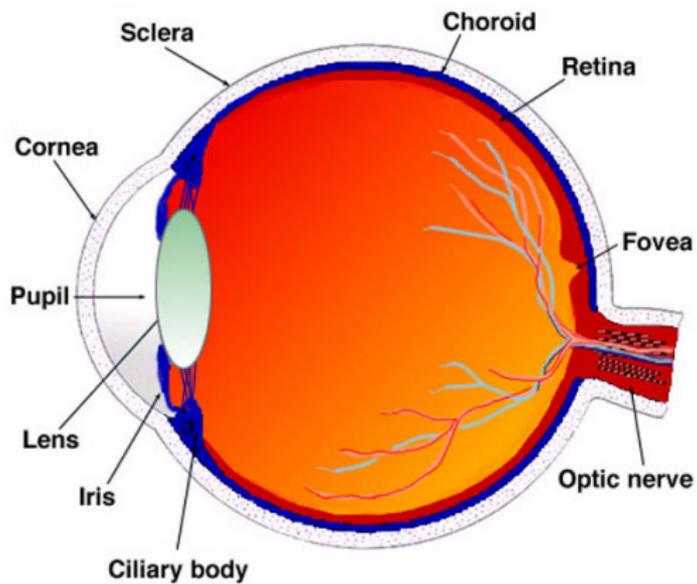
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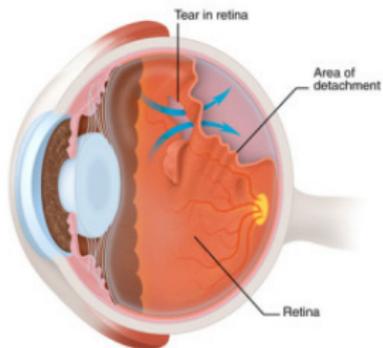


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Anatomy of the eye



Retinal detachment



Posterior vitreous detachment (PVD) and vitreous degeneration:

- more common in myopic eyes;
- preceded by changes in vitreous macromolecular structure and in vitreoretinal interface → possibly mechanical reasons.
- If the retina detaches from the underlying layers → loss of vision;

Rhegmatogenous retinal detachment:

- fluid enters through a retinal break into the sub retinal space and peels off the retina.

Risk factors:

- **myopia;**
- posterior vitreous detachment (PVD);
- lattice degeneration;
- ...

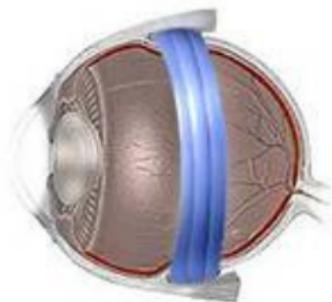
Scleral buckling and vitrectomy

Scleral buckling

Before



After



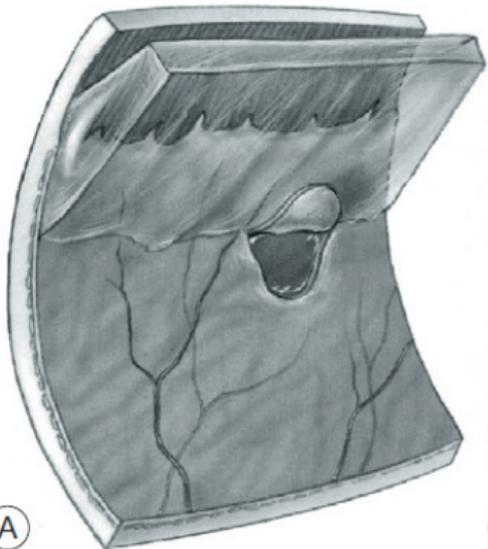
Scleral buckling is the application of a rubber band around the eyeball at the site of a retinal tear in order to promote reattachment of the retina.

Vitrectomy

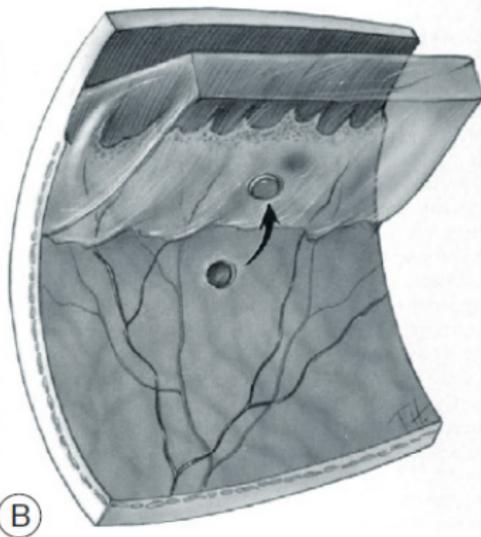


The vitreous may be completely replaced with tamponade fluids: silicon oils, water, gas, ..., usually immiscible with the eye's own aqueous humor

The retinal detachment: cases considered here

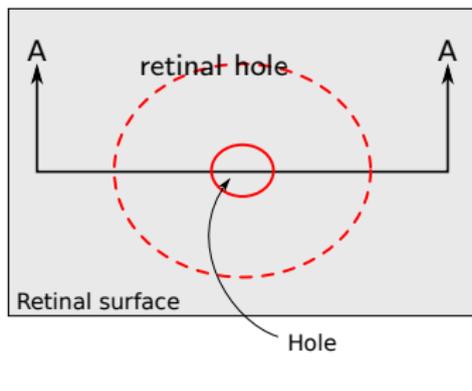
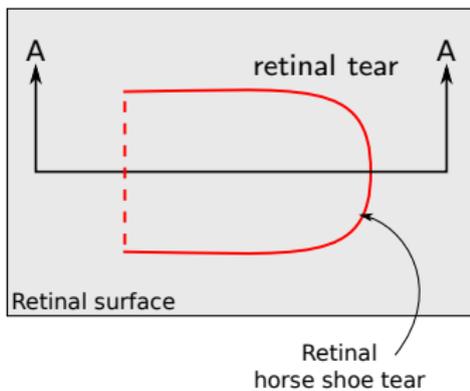


A) horseshoe tear (when large, $>90^\circ$, GRT),



B) retinal hole

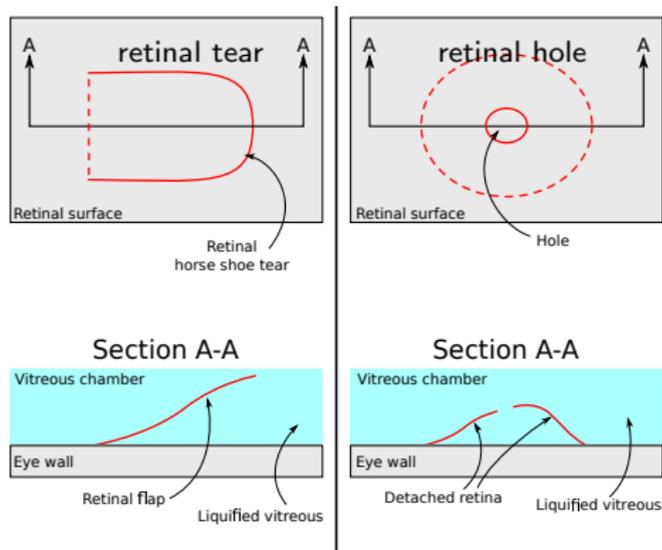
The retinal detachment: cases considered here



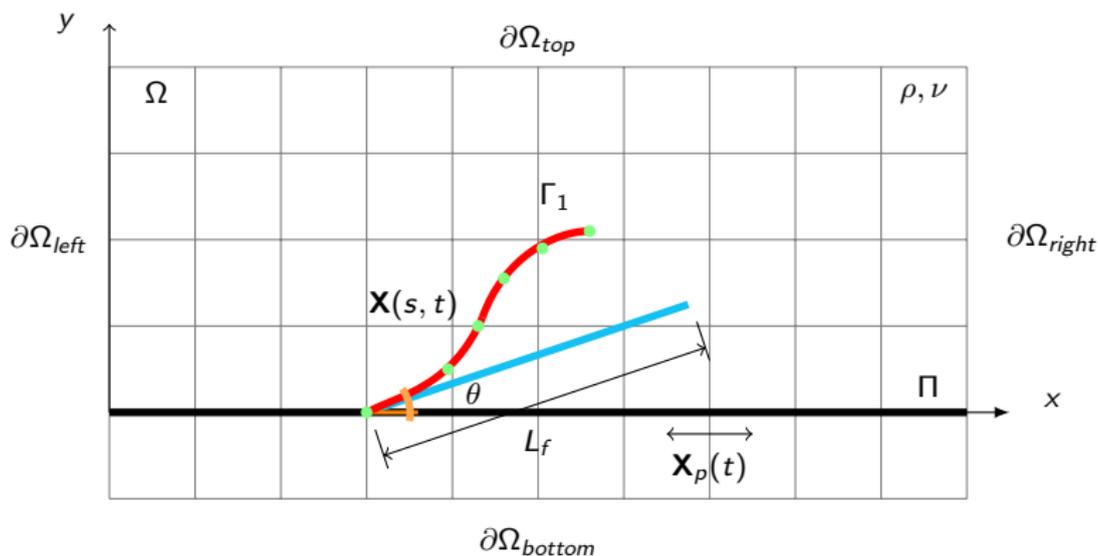
Motivation

Retinal tear and retinal holes are treated using surgery but it is not always clear what type of retinal break and under what conditions is more prone to further detach.

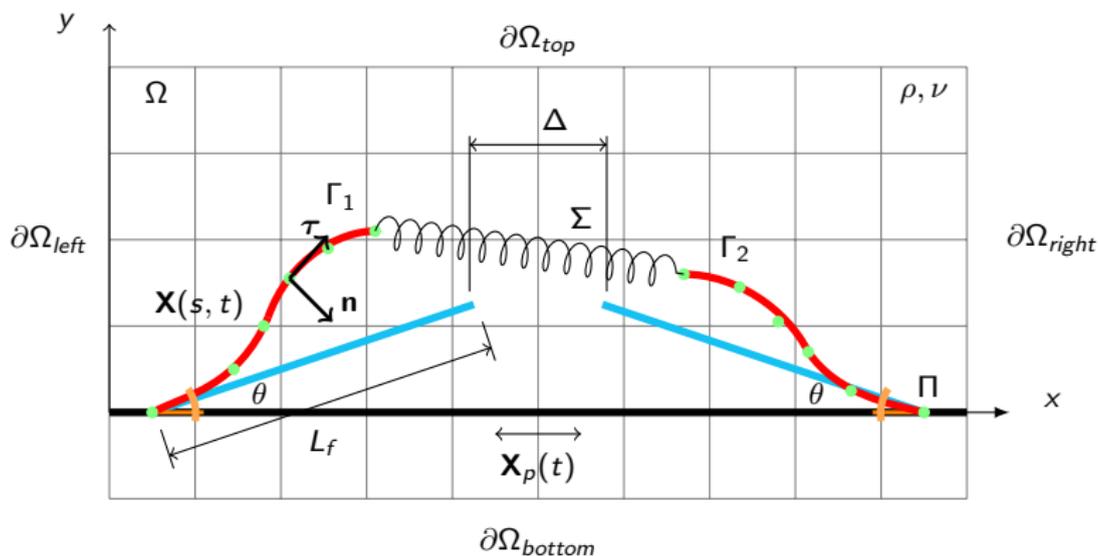
It would therefore be useful to parametrize (size, attachment angles, size of retinal hole, ...) different retinal breaks during eye motion and evaluate a measure of the **tendency to further detach**.



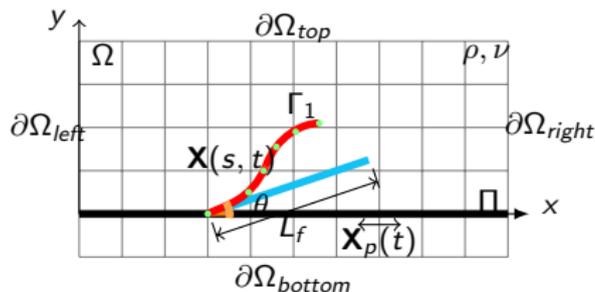
The model - tear configuration



The model - hole configuration



Governing equations



For the viscous incompressible fluid

$$\begin{cases} \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla p + \frac{1}{Re} \nabla^2 \mathbf{u} + \mathbf{f} \\ \nabla \cdot \mathbf{u} = 0 \end{cases},$$

Periodicity is imposed at $\partial\Omega_{left}$ and $\partial\Omega_{right}$, and symmetry at $\partial\Omega_{top}$ and $\partial\Omega_{bottom}$. Non slip boundary conditions are imposed on solid surfaces.

For the slender 1D structure

$$\rho_1 \frac{\partial^2 \mathbf{X}}{\partial t^2} = \frac{\partial}{\partial s} \left(T \frac{\partial \mathbf{X}}{\partial s} \right) - \frac{\partial^2}{\partial s^2} \left(K_b \frac{\partial^2 \mathbf{X}}{\partial s^2} \right) + \rho_1 \mathbf{g} - \mathbf{F}$$

The structure is clamped at a certain angle θ at the wall, which moves according to $\mathbf{X}_p(t)$. Incompressibility of the structure is imposed and non-slip/no penetration of the fluid is enforced.

Dimensionless parameters

The governing equations can be non-dimensionalized with the following characteristic scales:

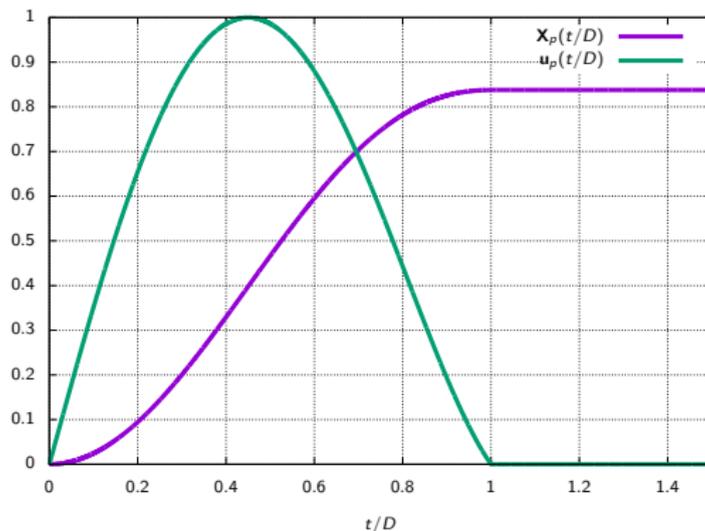
$$x^* = \frac{x}{L}, \mathbf{u}^* = \frac{\mathbf{u}}{U_\infty}, \mathbf{f}^* = \frac{\mathbf{f}L}{\rho_0 U_\infty^2}, \mathbf{F}^* = \frac{\mathbf{F}L}{\rho_1 U_\infty^2}$$

Doing so, several dimensionless parameters arises:

$$Re = \frac{U_\infty L}{\nu}, \quad Fr = \frac{gL}{U_\infty^2}, \quad \rho = \frac{\rho_1}{\rho_0 L}, \quad \gamma = \frac{K_b}{\rho_1 U_\infty^2 L^2}$$

Plate imposed motion

We model isolated rotations using the analytical relationship proposed by Repetto et al. (2005).



- The angle is 8°
- The maximum velocity is 0.061 m/s
- The duration is 0.045 s

Parameters used in the computations

| Quantity | Value | Reference |
|---------------------------------------|---------------------------------------|--|
| Properties of the retinal flap | | |
| Density ρ_S | 1300 kg/m ³ | |
| Length L | 1.5 – 2.5 mm | |
| Thickness | 70 μ m | Alamouti and Funk (2003), Foster et al. (2010), Ethier et al. (2004), Bowd et al. (2000), Wollensak and Eberhard (2004), Dogramaci and Williamson (2013) |
| Bending stiffness K_b | $2.98 \cdot 10^{-11}$ Nm ² | $Eh^3/12$ |
| Young's modulus E | $1.21 \cdot 10^3$ N/m ² | Jones et al. (1992), Wollensak and Eberhard (2004), Reichenbach et al. (1991), Sigal et al. (2005) |
| Properties of the fluid | | |
| Density ρ_F | 1000 kg/m ³ | Foster et al. (2010) |
| Dynamic viscosity μ | $1.065 \cdot 10^{-3}$ kg/ms | Foster et al. (2010) |

Table: Parameter values used for the simulations and corresponding references when available.

Dynamics for retinal tear

$$L=2 \text{ mm}, \theta = 33.6^\circ$$

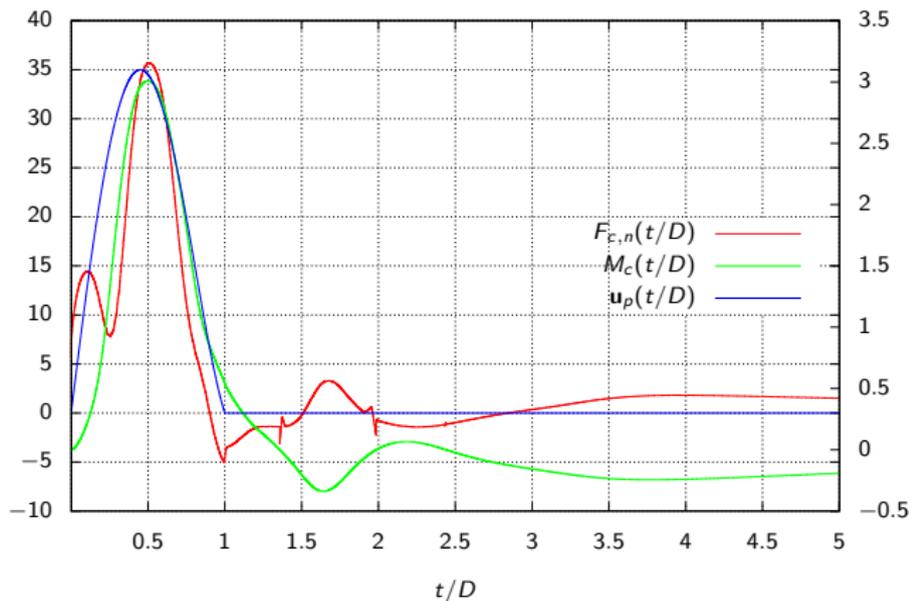
Movie 1

Dynamics for retinal hole

$$L=2 \text{ mm}, \theta = 33.6^\circ, \Delta = 0.17 \text{ mm}$$

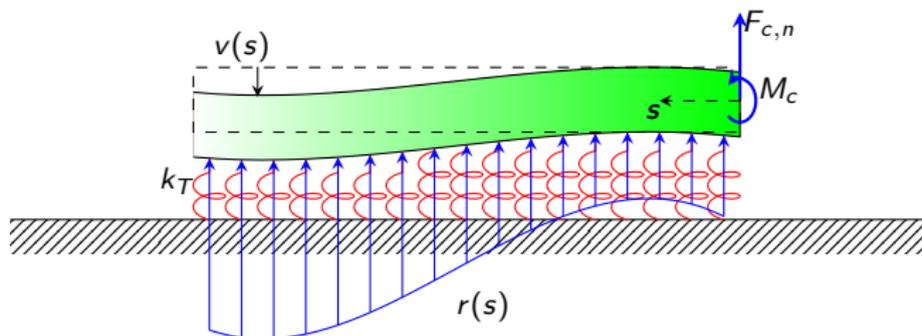
Movie 2

Clamping force and torque evaluation



We evaluate the wall-normal force ($F_{c,n}$) and torque (M_c) at the clamping point as a function of time. These values are then used to model the **tendency to further detach**.

Winkler theory



Semi-infinite foundation (in green) subject to a punctual force $F_{c,n}$ and torque M_c at the finite end, and supported by elastic spring of stiffness k_T (in red). The soil reaction $r(s)$ (in blue) is proportional to the foundation displacement $v(s)$.

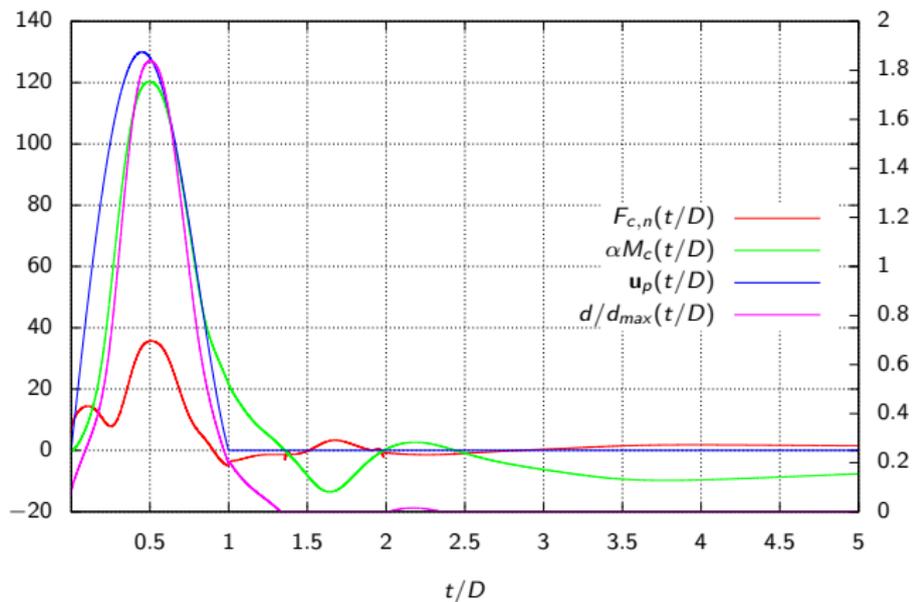
$$v(s) = \frac{e^{-\alpha s}}{2\alpha^3 \gamma} \{ \alpha M_c [\cos(\alpha s) - \sin(\alpha s)] + F_{c,n} \cos(\alpha s) \},$$

$$d = \max(v|_{s=0}, 0) = \max\left(\frac{\alpha M_c + F_{c,n}}{2\alpha^3 \gamma}, 0\right),$$

where α is the ratio between the soil spring rigidity k_T and the foundation beam stiffness γ .

d is the tendency to detach

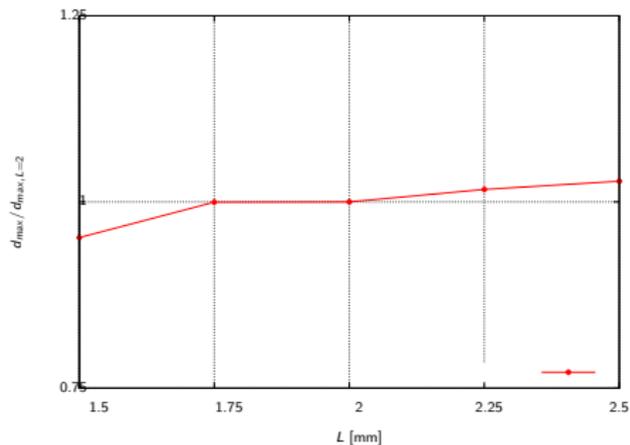
Tendency to detach



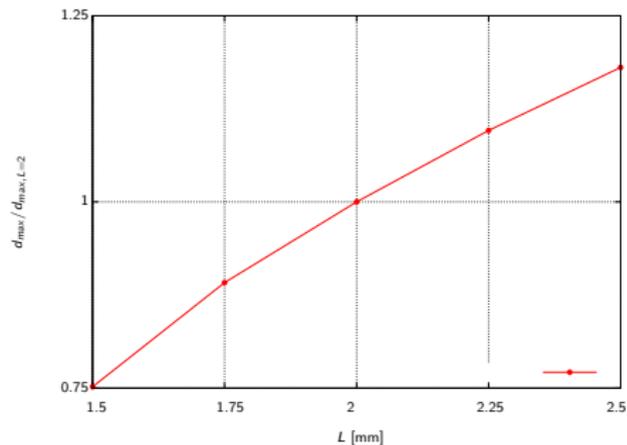
d attains a maximum value for a finite value of t/D

Different filament lengths L : maximum tendency to detach

clamping angle $\theta = 33.56^\circ$, $\Delta = 0.17\text{mm}$ (retinal hole)



Tear

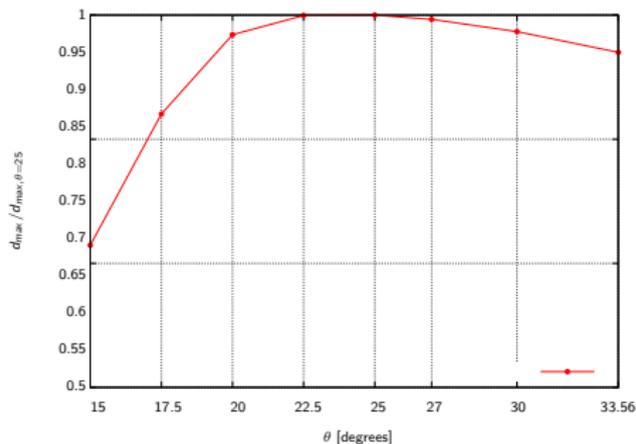


Hole

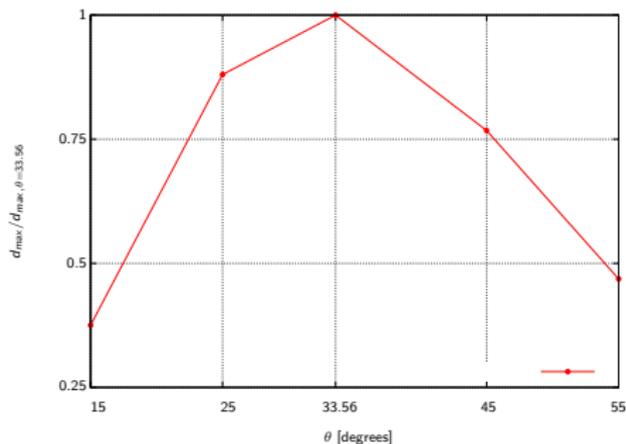
Increasing L increases the maximum value of d

Different clamping angles θ : maximum tendency to detach

length $L = 2$ mm, $\Delta = 0.17$ mm (retinal hole)



Tear

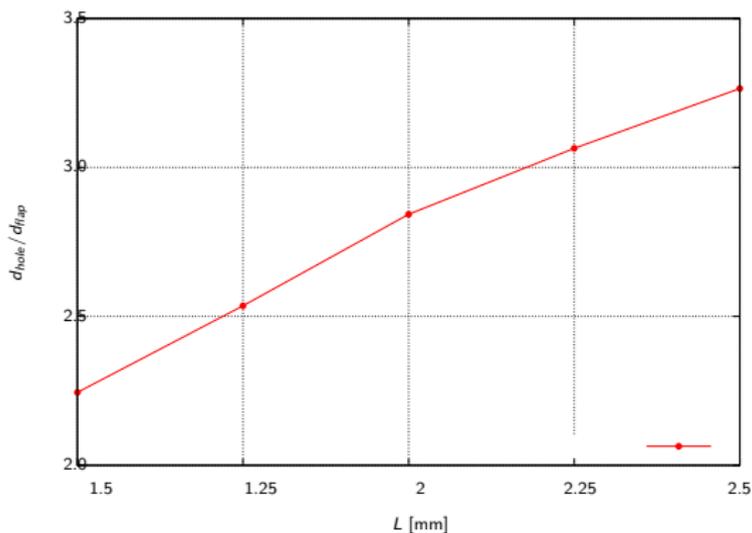


Hole

A maximum value of d is found

Comparison horseshoe tear & hole: maximum tendency to detach

clamping angle $\theta = 33.56^\circ$, $\Delta = 0.17\text{mm}$ (retinal hole)



The retinal hole is more prone to detach compared to horseshoe tear

Conclusions

- Numerical investigation of the tendency to further detach two types of retinal breaks (horseshoe tear & hole)

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- Achieved solving a fluid-structure interaction problem using a finite-volume code developed in Matlab[©] with an immersed boundary approach
- The parameters used are realistic for the human eye (according to the literature)
- The main results show:
 - Increasing the length L increases the tendency to detach (both hole & tear).
 - The maximum tendency to detach is found for a clamping angle of $\approx 25^\circ$ and $\approx 34^\circ$ for tear and hole, respectively.
 - The inter tip distance Δ (hole size) has little effect on the tendency to detach.
 - The tendency to detach of a retinal hole, compared to a tear, is 2 - 3 times larger for retinal filaments of 1.5 - 2.5 mm, with increasing values of d for increasing values of the filament length.

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- Collaborations with a surgeon confirms that these results will give useful guidelines for treatment of retinal breaks.

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